

KENNESAW STATE U N I V E R S I T Y



MTRE 1001L Vex Claw-Bot Competition

-Spring 2024-

By: Cary Chun Advisor: Dr. Muhammad Hassan Tanveer

The Mars Sample Return Mission

- Ambitious multination al project to bring Mars surface material to Earth
- VERY complex!



https://youtu.be/t9G36CDLzIg

Percy and Her Sample Tubes



- Collected and cached by Mars 2020 (Perseverance) Rover,
- This is the first leg of the Mars Sample Return Mission completed

Tubes on Mars

- 10 sample tubes are currently lying on the surface of Mars
- May need to be collected from surface at later date



Design Challenge: Fetch Rover



 Intended to collect cached tubes from surface

 Then transfer cached tubes to MAV

Slide By: Cary Chun

https://youtu.be/IAj9tXZyqS8?t=29

Vex Connection

- 10 sample tubes have been deposited for later retrieval
- Claw-bots will practice colleting and caching tubes
- (Names indicate where they came from)



Field Layout*

' Ground Obstacle

- - Aerial Obstacle

Sample Tube Location

Lander Canister



*this is only an approximate layout, actual layout may vary



Red Alliance

Blue Alliance

- Teams will be randomly assigned to one side of the field
- Watch out for potential obstacles not on these diagrams!



Game Objects

Mars Sample Tube (MST)



Also called "Tube"

Sample Return Canister (SRC)



Also called "Canister"

Anatomy of MST



- Top (gold end)
- Bottom (silver end)
- Real MST, far Left
- 3D-printed analogue, center left



Anatomy of SRC

- 12 holes for sample tubes
- Tubes may be inserted in any order
- Tubes must be inserted in proper orientation





MST Delivery (scoring points)

Incorrect











• 2 points scored!

• 0 points scored!

Order of Competition (1)

(1) Autonomous Period

- "3, 2, 1, GO!"
- 30 seconds
- Must be activated by remote
- After activation, remote put down
- Robot touching most tubes wins



Order of Competition (2)



(2) Manuel Period

- "3, 2, 1, GO!"
- 2 minutes*
- Pickup controllers and start scoring

*May be changed at any time

Knowledge Test!

Blue Alliance



Red Alliance



Blue Alliance



Red Alliance



Blue Alliance



Red Alliance



Blue Alliance



Red Alliance



Blue Alliance







Blue Alliance











3 tubes x 2 points/tube =







4 tubes x 2 points/tube =







Canister Cannot Close!



Please Review Full Rules

MTRE 1001L		Spi	vring 2024
	MTRE 1001L Com	petition	
_	Wann Cannals Batanan Fata	L D	
Motivation	MTRE 1001L		Spring 2024
The Mars San	(00.5) 75		
robotic planetary exp	(GR5) - The ga During the autonomou	ime will consist of one scoring is period, the robot that is in play	g object, the Mars Sample Tubes (MST).
the first mission to re scientists on Farth. To	MSTs will be declared	the winner. Successful deliver	ry of an MST to the Sample Return Canister
and surface rovers wi	(SRC) will rest		
rover, which has beer	end of the man		
Ten such tubes have 1		MTRE 1001L	Spring 2024
epic MSR mission.	(GR6) -		
For this year's	of time. In the consertion of MS	(RR5) – Edges	of robot should be rounded or covered in padded material, to ensure the
"Fetch Rover" which	of time, no sco	safety of all participant	R.
waiting Mars Ascent		(RR6) – 1	MTDE 10011 Series 2024
prototype rover to co	(GR7) -	isotopes.	Spring 2024
and you will need to a	judges, an accid	(RR7)	
collect and fetch as n	official. Alliand	issues identified	During the competition, design teams will be randomly assigned to either the Red or Blue sides
space, the rover must	platers purpose	parts fall off the	of the competition field. Teams must be prepared to compete on either field arrangement.
onboard power to cor	(GR8) -	until it can pass.	Game Objects
NASA's Fetch Rover	Violation of thi		[Mars Sample Tubes (MSTs)]
	(CD0)	Competition Fie	Also colled "Tube" for short
Game Rules	(GR9) -	The commotition	 Prine edited Tube for short "Toe" is colored and and is wider
GR1) - Match	ground or a tab	Blue Alliance T	 rop is colored gold and is wider "Bottom" is colored silver and is thinner
will last 30 seconds a	contact with ea	Ditte Athance, 11	Must be incerted into SP/C Bottom first
final score. The manu	winner of the a	F	 wast of inserted into site, bottom inst
period.	ruling on the at	r -	
(GR2) - Mate	into the manual		
robot each.	before the indic	-	
	(GR10)		[Sample Return Canister (SRC)]
(GR3)- Robot	be acting in a n		Alter all all Carles 2 for these
intentional damage or		_	 Also called "Canister" for short
(CP4) Poho			Exterior is color coded to each alliance Contains 12 holes for MSTs
color tape on floor) ?	Robot Rules		 Contains 12 notes for MS1s No objects may stick up part the flat lid at the and of time
alliance's side. Manig	(RR1) -	•	 No objects may suck up past the that nd at the end of time
	(RR2) -	Park and a second	
	controller.	to the long dista:	
	(RR3) -	samples and obs	
	brain. No other		
	(004)		
	(RR4) - deno. with the		
	depo, with the		
			Searing
			Scoring Decision
			[Autonomous Period]
			 Robot with most MSTs physically in contact with any part of the robot will be declare winner
			 Winner of autonomous period awarded 5 points
			Examples of
			Page 4 of 6

- See detailed competition document for additional rules
- Should be available on D2L?
- Ask questions if they arise!

Next Task: Sketches

- Remember that limited resources are available for use
- Consider how to use sensors for autonomous period
- (Make sure to test sensors before implementation)



Link to Tube CAD File





Modular Aerospace and Robotic Systems